

MASSACHUSETTS INSTITUTE OF TECHNOLOGY  
DEPARTMENT OF MECHANICAL ENGINEERING  
CAMBRIDGE, MASSACHUSETTS 02139

**2.29 NUMERICAL FLUID MECHANICS— SPRING 2007**

**Problem Set 1**

Posted 02/08/07, due Thursday 4 p.m. 02/23/07

**Problem 1.1 (40 Points)**

Solve the below problems from “Chapara and Canale” textbook:

- 1.11
- 2.13, 2.15: Print the program and the result
- 3.1, 3.7, 3.9
- 4.5, 4.8, 4.15, 4.19

**Problem 1.2 (10 Points)**

Review MATLAB help on these commands:

- realmin
- realmax
- eps

Now use the eps for both single and double accuracy levels and compute the below series by calling a RECURSIVE function. Compute the relative and absolute accuracy and compare it by errors associated with numerical representation in your computer.

$$2 = 1 + \frac{1}{2} + \frac{1}{2^2} + \frac{1}{2^3} + \frac{1}{2^4} + \dots$$

**Problem 1.3 (10 Points)**

For a uniform inviscid flow passing a sphere with radius “R”, the potential field is given by:

$$\phi(r, \theta) = U \left( r + \frac{R^3}{2r^2} \right) \cos(\theta)$$

Here U is the far field velocity and the far field pressure is zero.

- Compute the fluid velocity and plot it.
- Discuss and evaluate the boundary conditions in infinity and in  $r=R$ .
- Compute the pressure field and plot it.
- Compute the drag force.

**Problem 1.4 (30 Points)**

The  $\sec(x)$  is defined as the inverse of  $\cos(x)$ :

$$\sec(x) = \frac{1}{\cos(x)}$$

- a) Drive the Taylor series for both  $\sec(x)$  and  $\cos(x)$  around  $x=0$ . Note that the coefficients of  $\sec(x)$ 's Taylor series are somehow complicated so you might need a program to evaluate them.
- b) Write down the numerical value of 1st eight coefficients of  $\sec(x)$ 's Taylor series.
- c) Now compute the by its Taylor's series expansion. Sum up the series from the 1st term until the  $n$ th term; when the last term is smaller than "esp". Report "n" beside absolute and relative error.
- d) Discuss whether the error is smaller than "eps" or not. Now repeat the part c; but stop the summation when for the first time, the last nonzero term is smaller than "esp" and is approximated by zero in your computer.
- e) Repeat part c, but this time stop the summation when for the 1st time adding a nonzero term does not change the value of  $\sec(x)$ . Can you somehow approximate an upperbound for the error just from the numerical representation?
- f) Repeat part c, d and e when  $\sec(x)$  and series terms are represented by "single" data type (instead of default MATLAB data type, "double", which were used in previous parts).
- g) Repeat part c, d and e; but this time, with known  $n$ , sum up the series from  $n$  to 1. Do you get better results? Discuss.

In practice the summation stops whenever either the condition e or the condition c (more conservatively d) is satisfied. From now on implement both conditions at the same time for computing both  $\sec(x)$  and  $\cos(x)$ .

- h) Compute  $\sec(x)$  by inverting the  $\cos(x)$ . However, compute the  $\cos(x)$  from its series expansion. Report "n" as well as absolute and relative errors.
- i) Which way of computing  $\sec(x)$  is better? Discuss. If we want to use a reverse summation scheme; can you estimate the  $n$  by which the summation should start?
- j) Compare  $n$  and errors for computing  $\sec(x)$  by its own series versus  $\cos(x)$  series for cases when  $x = \frac{\pi}{8}, \frac{3\pi}{8}, \frac{\pi}{16}, \frac{7\pi}{16}$ .